

Finite Element Concepts

Exact Differential Equations + BC to
Approximate Matrix Equations + BC

Integral Analytic Approaches

- 1750 System energy + BC →
Energy methods + BC (Euler) →
Integral form + BC
- 1750 Differential equations + BC →
Variational calculus + BC (Euler) →
Integral form + BC
- 1950 Differential equations + BC →
Galerkin's method + BC →
Integral form + BC

Equivalent Forms

- Exactly solving the integral form, + BC, yields the same unique solution as exactly solving the differential equation, + BC (for linear problems).
- **Galerkin's method** can be used to build integral forms for non-linear differential equations as well.

Energy Methods

- (Static) **system energy** = potential energy (strain energy) – external mechanical work
- All are defined with respect to the **displacements** (the unknowns)
- Strain energy uses the material properties
- Work uses the external forces (sources)
- **Equilibrium** → Energy is minimized by the displacements that satisfy the BC (on displacements)

Example Linear Spring

- Linear spring of “stiffness” k is fixed at one end (BC) and displaced an amount x by end force f , find the equilibrium displacement.
- Energy: $E = \frac{1}{2} k x^2 - f x$
- Minimize w.r.t. x : $\partial E / \partial x = 0$
- Equilibrium: $k x - f = 0$, so $x = f / k$

Galerkin's method

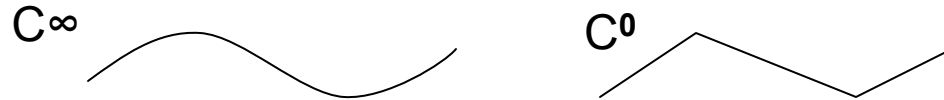
- Let $(\mathbf{DE} = \mathbf{0})$ be the differential equation of equilibrium over volume V , subject to \mathbf{BC} . The \mathbf{DE} involves the solution, \mathbf{u} and/or its gradient $\partial\mathbf{u} / \partial\mathbf{x}$, and source terms
- Let \mathbf{W} be a weighting function over space
- Weighted residual: $\mathbf{IE} = \int_V \mathbf{W}^*(\mathbf{DE}) dV = \mathbf{0}$, subject to \mathbf{BC}
- Galerkin: Pick $\mathbf{W} = \mathbf{u}$, so error is “orthogonal” to the solution

Finite Element Method (1960)

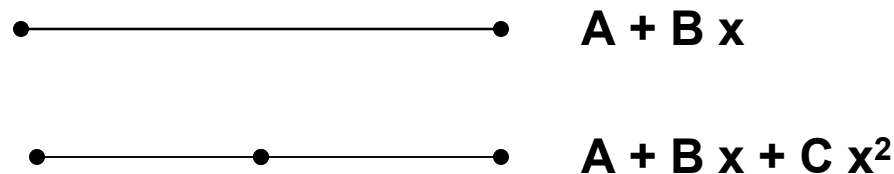
- Requires a known integral form, & BC.
- Assumes the spatial form of an approximate solution to $\mathbf{u}(\mathbf{x})$, and thus to its gradient $\partial\mathbf{u} / \partial\mathbf{x}$ (and for \mathbf{W})
- Forms a mesh of volume elements and nodal points over V (and its boundary)
- In each element interpolates $\mathbf{u}(\mathbf{x})$ from its values (unknown) at the element's nodes, say \mathbf{u}_e , a subset of all unknowns, say \mathbf{U}

Piecewise Interpolation

- The FE approximation is only piecewise continuous (C^0) at the nodes and element faces, but continuous (C^∞) inside the element.



- Count nodes on element edge: 2 for linear (constant gradient), 3 for quadratic (linear gradient)



FE Algebraic Equations (1)

- \mathbf{U} are unknowns at all points and we need an algebraic system to compute them
- Split the integral into the sum of the integrals over the elements:

$$\mathbf{I}\mathbf{E} = \int_V = \sum_e \int_V^e = \mathbf{0}$$

- Substitute the approx. sol. $\mathbf{u}(\mathbf{x}, \mathbf{U})$ into the integral form, factor out the \mathbf{U} , integrate the spatial form for the element matrix and vectors, $\mathbf{k}^e * \mathbf{u}^e = \mathbf{f}^e$

FE Algebraic Equations (2)

- Add up (assemble) all the element matrices and vectors into the large system algebraic equations of equilibrium: $\mathbf{K} * \mathbf{U} = \mathbf{F}$
- Apply the **BC** to the equations to get a smaller algebraic system: $\underline{\mathbf{K}} * \underline{\mathbf{U}} = \underline{\mathbf{F}}$
- Solve this final system: $\underline{\mathbf{U}} = \underline{\mathbf{K}}^{-1} * \underline{\mathbf{F}}$
- Plot \mathbf{U} . Recover the element gradients and plot them

Local FE Error

- Local error at a point is the product of the element size, h , and the rate of change of the gradient of the solution
- Need a fine mesh where the stress concentrations gradients or the heat flux gradients are high
- Mesh is controlled by “splitting” the solid model

Conduction through a wall

- Thickness L , conduction k , area $A = 1$, heat source per unit volume Q , inside temperature $u_1 = 0$, find outside temp u_2 .

$$\mathbf{k}^e * \mathbf{u}^e = \mathbf{f}^e$$
$$\frac{kA}{L} \begin{vmatrix} 1 & -1 \\ -1 & 1 \end{vmatrix} \begin{vmatrix} u_1 \\ u_2 \end{vmatrix} = \frac{QAL}{2} \begin{vmatrix} 1 \\ 1 \end{vmatrix}$$

$$kA / L [1] u_2 = QAL / 2 \{1\}$$

$$u_2 = QL^2 / 2k$$

