

# Introduction to Search

## *Starting Chapter 4*

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COMP 200, Lecture 15

*Rice University*

*Fall 2004*



## Search as a Paradigm

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Algorithms texts often focus on two problems

- Search — finding some specified object in a data structure
- Sort — ordering the elements of some data structure

These two problems have an intuitive structure and play a critical role in many algorithmic problems

Chapter 4 of the Text

- Introduction to algorithmic paradigms
- First set of examples are searches and sorts

## Back to Binary Trees



In Lecture 13 (Friday) we talked about trees

- Focus on binary trees
- Used to represent many things
  - ◆ Ordered sets (dictionaries)
  - ◆ Syntax trees (sentence diagrams)
  - ◆ ...
- Search in a binary tree is an important algorithm
  - ◆ Traversal — enumerating the nodes in some order
  - ◆ Genuine search — efficiently finding a specific node

```
; a binary tree node (btn) is either
; empty
; or a structure
; (make-node data left right)
; where data is a name and left & right are btn
(define-struct btn (data left right))
```

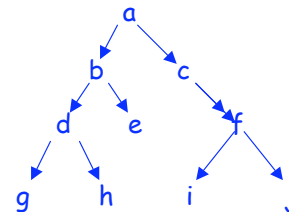
## Traversing a binary tree



Handful of ways to traverse a tree

- Specific pattern of recursion dictates a “traversal order”

```
; Walk1 : btn -> boolean
; Purpose: traverse a btn
(define (Walk1 fee)
  (cond
    ((empty? fee) true)
    ((node? fee)
     (begin
        (Walk1 (node-left fee))
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        (do something with fee itself) ))
  ))
```



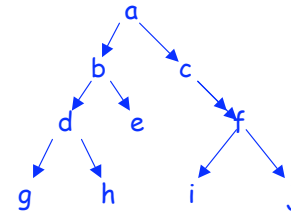
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Produces the order

(g h d e b i j f c a)

which we call "preorder"

Left-to-right preorder

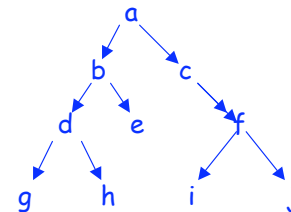
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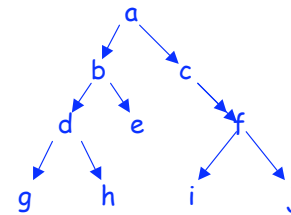


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Produces the order

(a b d g h e c f i j)

which we call "postorder"

Left-to-right postorder



## Traversing a binary tree

Both of these orders are "depth-first" searches

- Dive deeper in the tree before going laterally across a level
  - ♦ Use a stack-like action to keep track of position in the traversal

```
push ( "root" node of tree )
while (stack is not empty)
  current ← pop()
  push (right child of current)
  push (left child of current)
  process current
```

Stack version of postorder walk

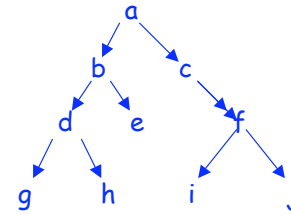
What about other orders?

## Traversing a binary tree



### Breadth-first search

- Depth-first dives to the bottom
- What if tree is huge? Not finite?
  - ♦ Search trees in a chess game
  - ♦ Combinatorial number of nodes
  - ♦ Consider alternatives to limited depth
- A breadth-first search exhausts a level before moving down
  - ♦ Breadth first order would be (a b c d e f g h i j)



Can we write a breadth-first search for our tree?

- ♦ Depth-first search models a stack; breadth-first uses a queue

## Traversing a binary tree

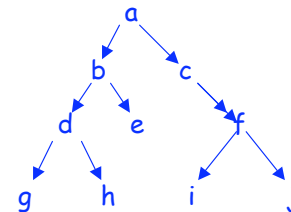


### Breadth-first search

- Queue is first-in, first-out
- Same push() pop() abstraction

```
current ← root
while (current is not empty)
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Breadth-first search



## Traversing a binary tree

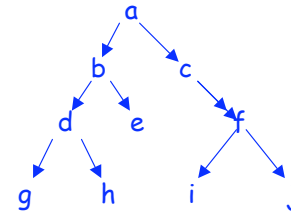


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Breadth-first search



Queue contains (over time)

[b, c] [d, e] [f] [g, h] [i, j]

forcing the "process" step into alphabetical order ...

## Search in a binary tree



Important to consider the data structure & its properties

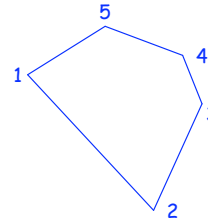
- Unordered tree
  - ♦ Use one of the traversals — depth-first, breadth-first
  - ♦ Amounts to exhaustive search (British Museum Algorithm)
  - ♦ In some cases, it's the best we can do
- Ordered tree
  - ♦ Property defined on value of node & its children
  - ♦ Treesort produced such a tree
  - ♦ Can limit recursion to relevant subtree (child + its descendants)
  - ♦ Significantly reduces cost of search

## Other kinds of search



Finding maximal distance in a polygon (Chapter 4)

- Assume a simple convex polygon
  - ♦ All angles  $< 180$  degrees
- BMA would compute distance between all pairs

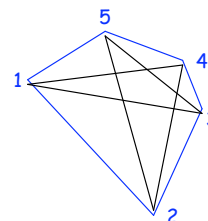


## Other kinds of search



Finding maximal distance in a polygon (Chapter 4)

- Assume a simple convex polygon
  - ♦ All angles  $< 180$  degrees
- BMA would compute distance between all pairs
  - ♦ Edges:  $(1,2), (2,3), (3,4), (4,5), (5,1)$
  - ♦ Interior lines:  $(1,3), (1,4), (2,4), (2,5), (3,5)$
  - ♦ Gets much more expensive as number of points rises

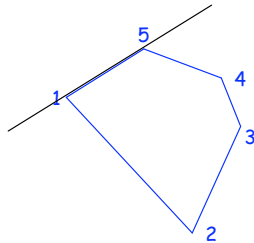


We find the answer while looking at fewer lines

## Other kinds of search



Finding maximal distance in a polygon (Chapter 4)

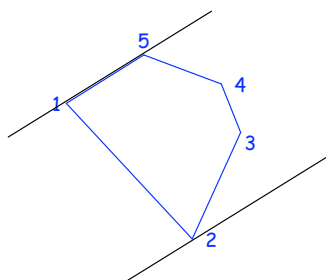


1. Draw a line along one edge

## Other kinds of search



Finding maximal distance in a polygon (Chapter 4)

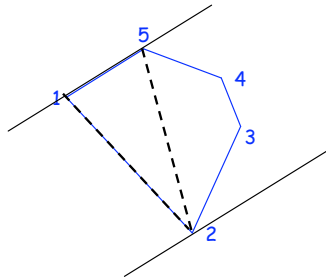




## Other kinds of search



### Finding maximal distance in a polygon (Chapter 4)

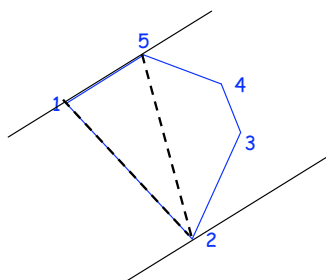


1. Draw a line along one edge
2. Find farthest extent along a perpendicular (Book's parallel line moving inward from infinity)
3. Measure 2 lines defined by the 3 points

## Other kinds of search



### Finding maximal distance in a polygon (Chapter 4)



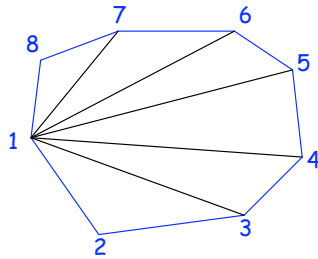
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3. Measure 2 lines defined by the 3 points

Repeat 1 to 3 for each side, in sequence

For each edge in the polygon, it considers 2 distances

- Considers  $2n$  distances, among (potentially)  $n^2$  choices
- Pentagon is a low-complexity case
  - ♦ Has only two non-edge distances per node
  - ♦ Higher-degree polygons better show the worst case complexity

## Polygonal distance



Irregular octagon

Each node has five non-edge distances

⇒  $8 \times 5 / 2$  chords + 8 edges

⇒ 28 distances by BMA

⇒ "Better" search is  $2 \times 8$  edges

⇒ 16 distances by "better algorithm"

Bottom line:

⇒ Using contextual knowledge can reduce the cost of search (& other algorithms)