#### Design Patterns for Self-Balancing Trees

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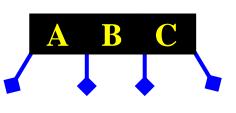
# Motivations

- Classic self-balancing tree structures
  - 2-3-4 tree (see next slide)
  - red-black tree (binary tree equivalent of 2-3-4 tree)
  - B-tree (generalized 2-3-4 tree)
  - Difficult and complex. Where's the code?
- **\*** What's the proper abstraction?
  - Need to decouple algorithms from data structures.

#### A 2-3-4 Tree is...

Empty

- **0-State:** no data element + no sub-trees.
- **Non-Empty**, in 3 possible states:
  - **1-State:** 1 data element + 2 sub-trees.
  - **2-State:** 2 data elements + 3 sub-trees.
  - **3-State:** 3 data elements + 4 sub-trees.



A

A

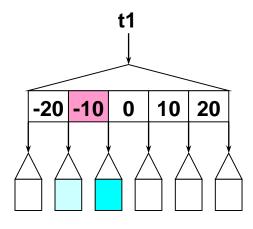
B

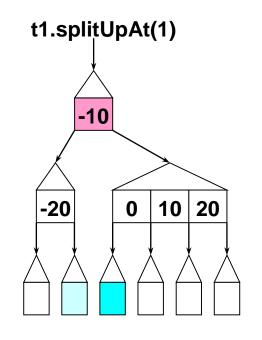
### Variant vs. Invariant Operations

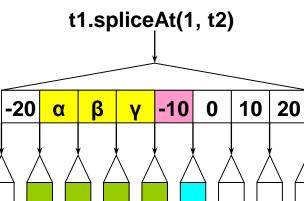
- \* Self-balancing insertion is <u>not</u> an intrinsic (invariant) operation of a tree.
- \* What are the invariant operations?
  - Gettors & Constructors.
  - Constructive and Destructive operations:
    - \* Constructive: Splice a tree into another.
    - \* Destructive: Split a tree into a 2-state.

# **Splittin' and Splicin' Split Up: Splice:** A B C Intrinsic operations on the tree STRUCTURE, not the data!

#### **Structural Operations**







t1.splitDownAt(1)

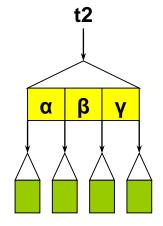
0

10

20

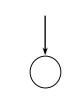
-20

-10



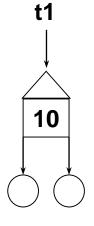
#### **Con/De-struction**

t1.splitDownAt(0)



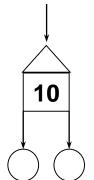
# t1.splitUpAt(0)

10

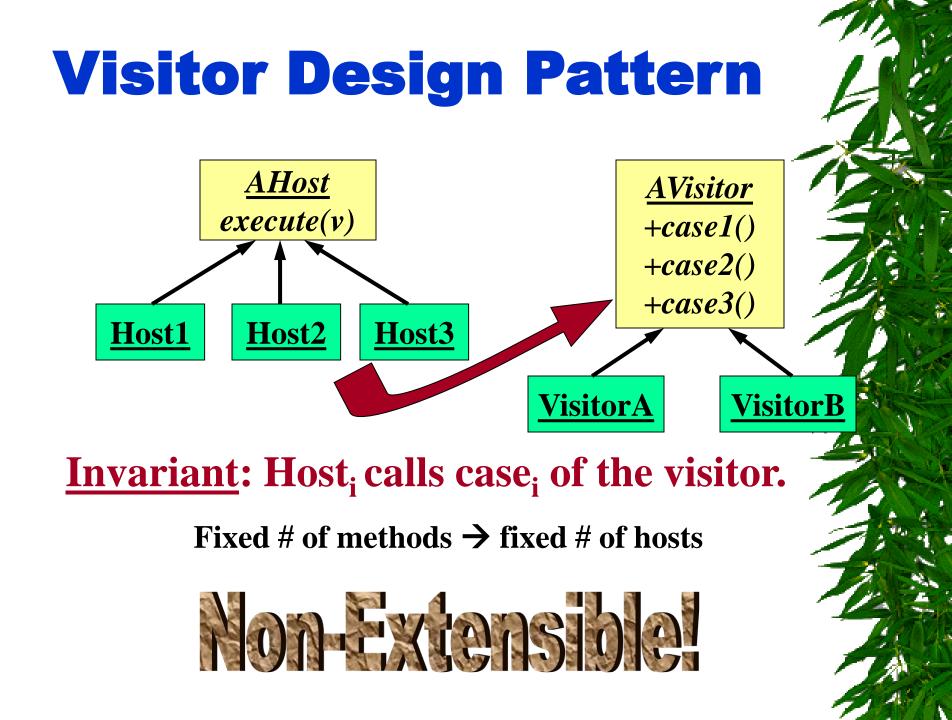


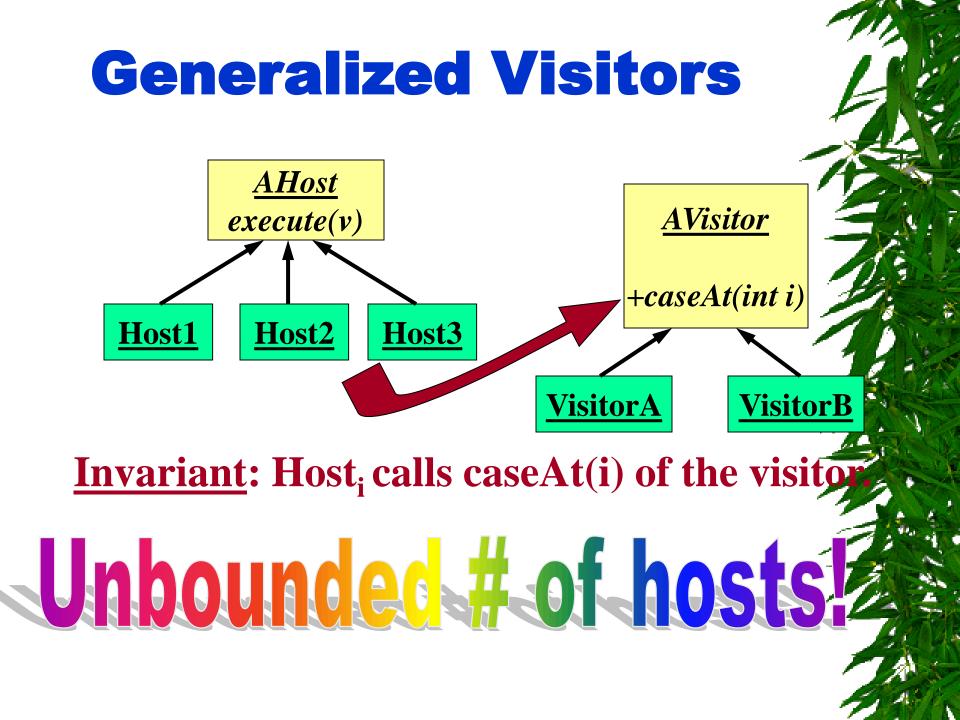
**t2** ↓

#### t2.spliceAt(0, t1)

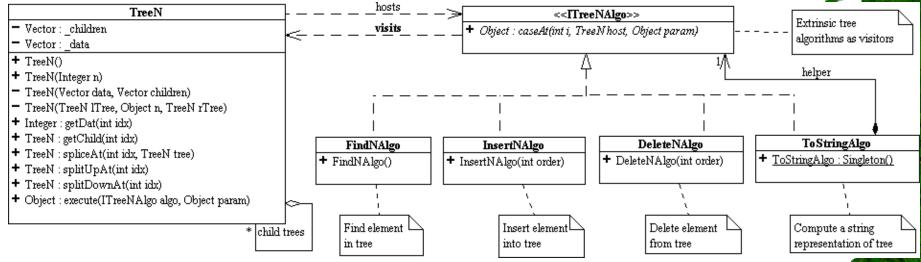






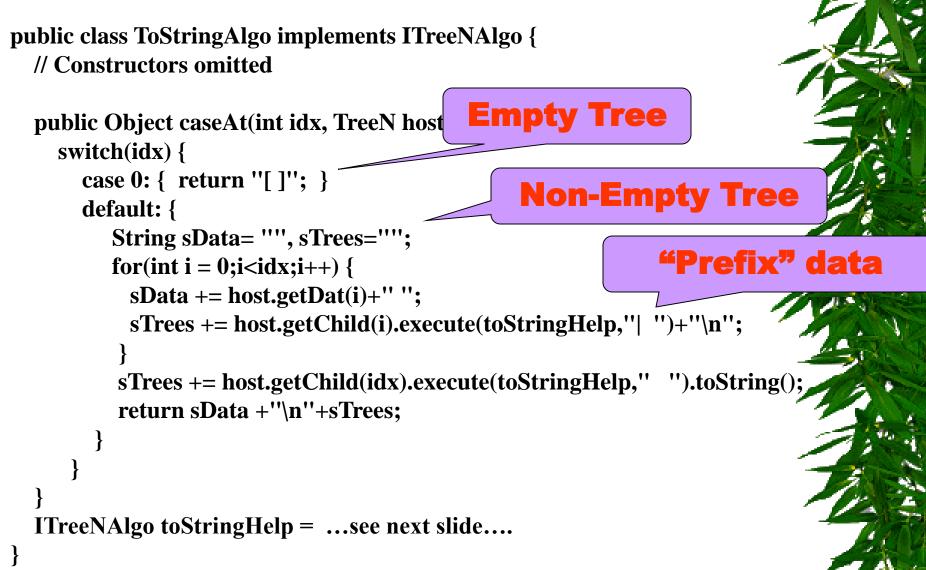


#### **TreeN and Algorithms**

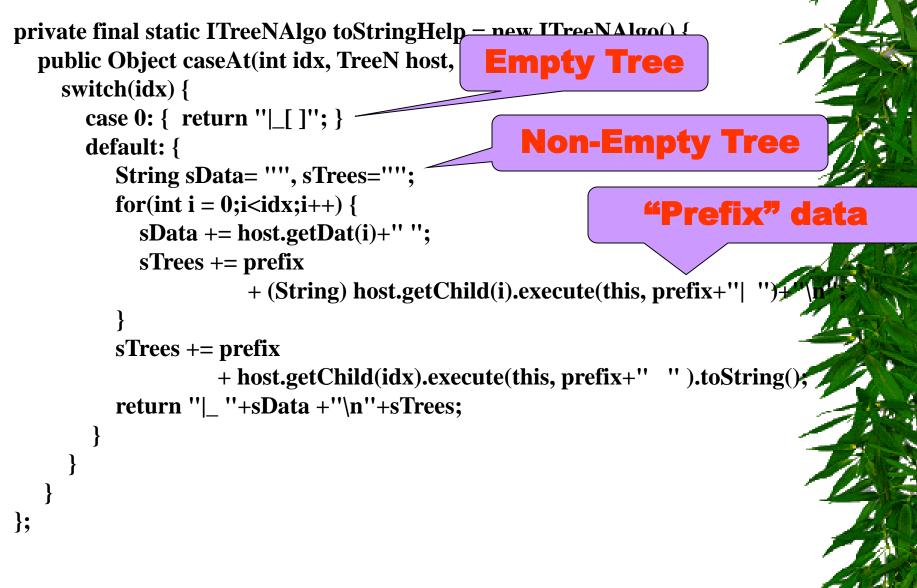




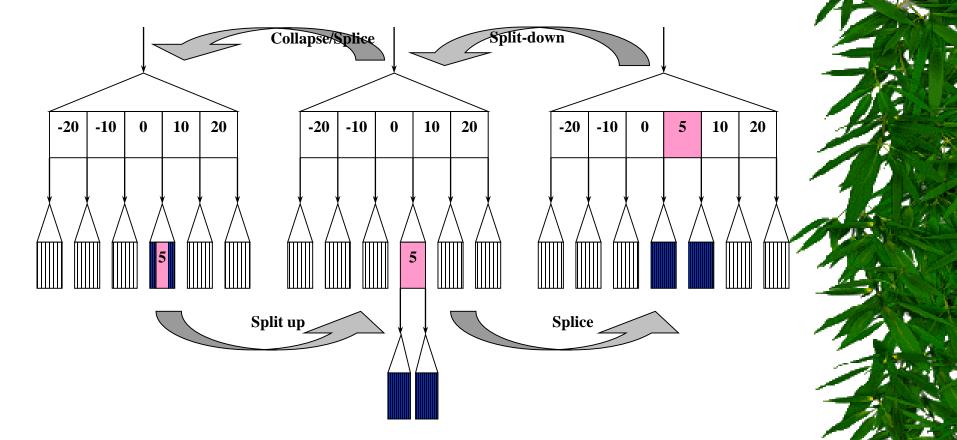
# toString() Algorithm



#### **ToString()** Helper

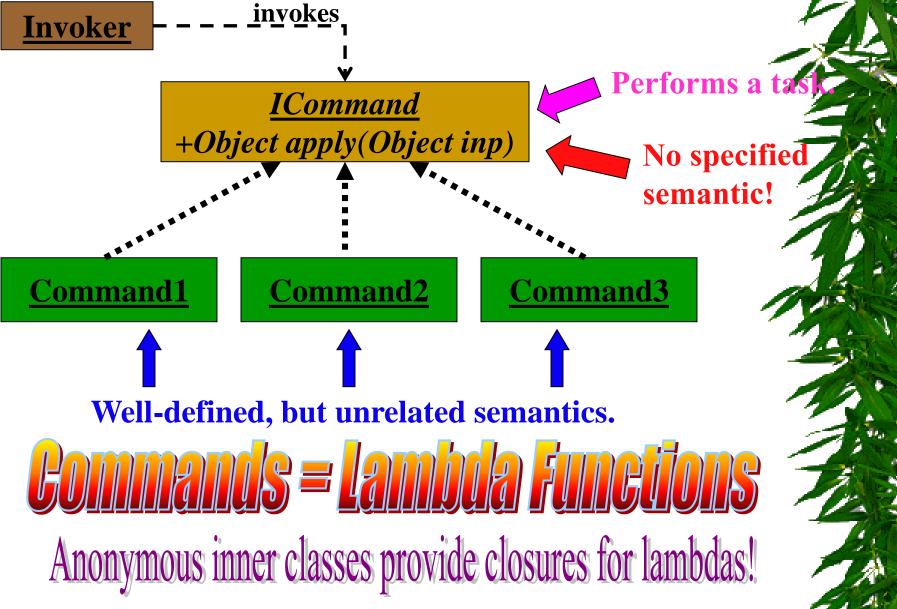


### **Vertical Data Transport**



No net height change except at root and leaves!





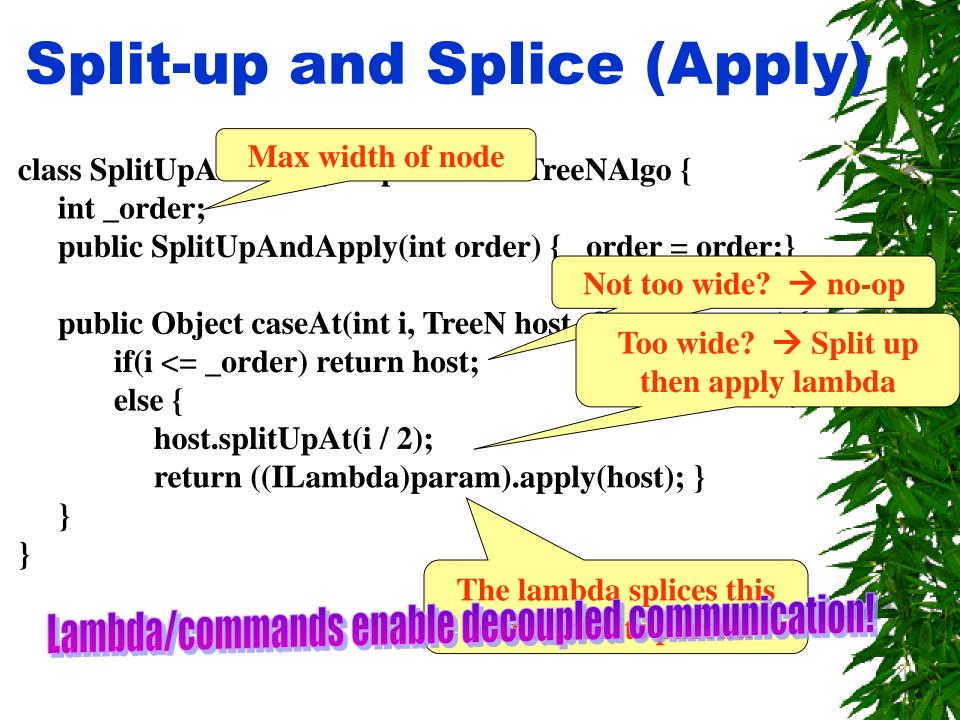
#### **Insertion Heuristics**

Insertion must take place at the leaf.
Tree must grow only at the root.

Must transport data from the leaves to the root without affecting the height balance. **<u>Problem</u>: If a child node is too wide, it needs to split up and splice into its parent, but...</u>** 

- The child node does not know where to splice into its parent
- The child does not even have a reference to its parent.

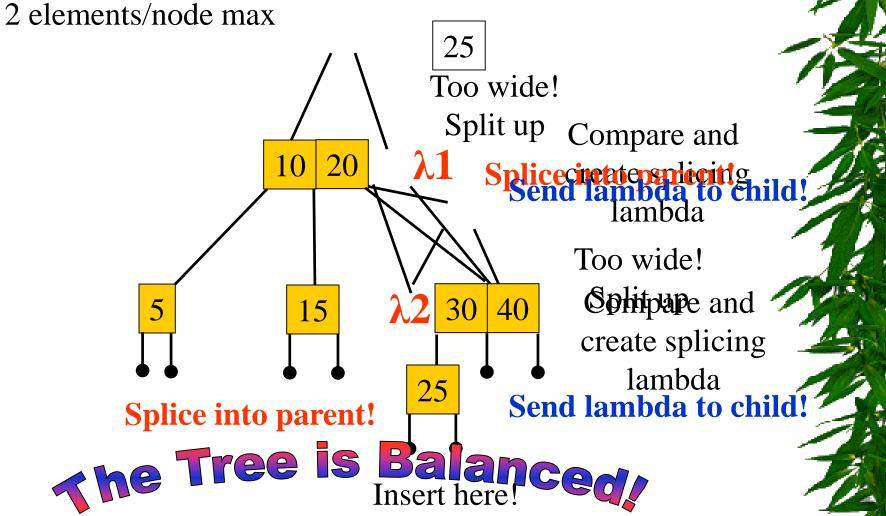
<u>Solution</u>: Pass a command (lambda) forward from the parent to the child during the recursive call.

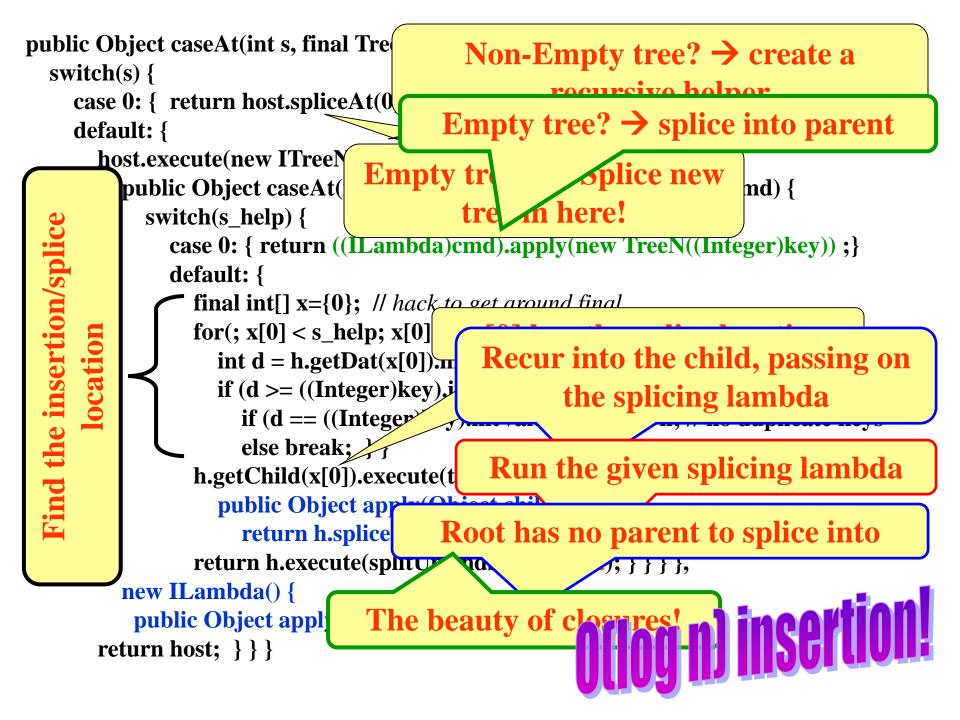


### **Insertion Algorithm**

- Find insertion point at the leaf and splice new data in.
- Use Split-and-Apply visitor to transport excess data upwards.
  - Visitor passed as parameter to recursive call.
  - Non-root: split-and-splice
  - Root node: split-and-no-op will cause entire tree to grow in height.
  - Abstract the splice/no-op as a command passed to the visitor!

#### **Insertion Dynamics**





#### **Deletion Heuristics**

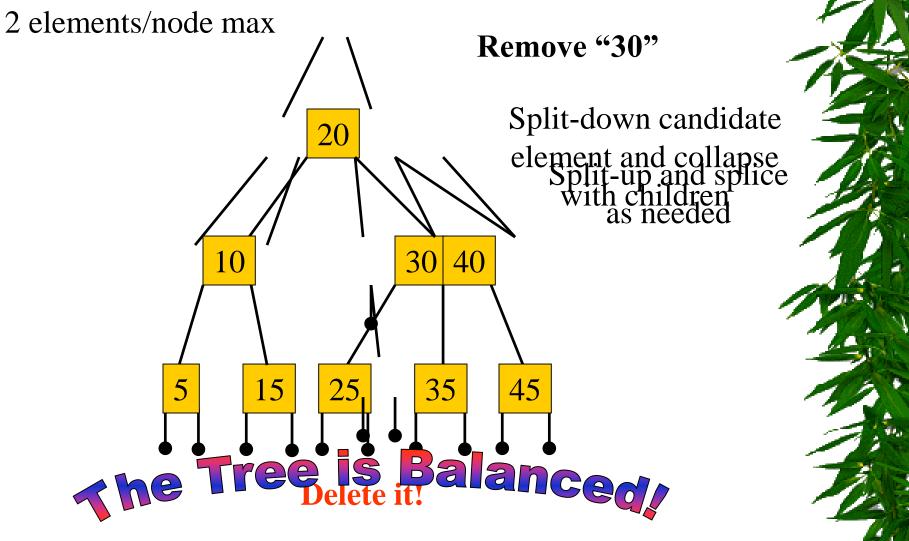
- **\*** Deletion only well-defined at leaf.
- \* Data might exist anywhere in the tree.
- \* Tree can only shorten at root.
- → Push "candidate" data down from the root to the leaves.
- → Bubble "excess" data back to the root.

Must transport data from the root to the leaves and from the leaves to the root without affecting the height balance.

#### **Deletion Algorithm**

- Identify candidate data
  - split down at candidate and collapse with children.
  - If root is a 2-node, then tree will shorten.
- Data to delete will appear as 2-node below leaves.
- Use Split-and-Apply to transport excess data upwards.

#### **Deletion Dynamics**



#### Conclusions

- Proper abstraction leads to
  - Decoupling
  - Simplicity
  - Flexibility & extensibility
- Generalized Visitors open up new possibilities,
- Self-balancing trees teach
  - Abstract decomposition
  - Design patterns
  - Component-frameworks
  - Lambda calculus
  - Proof-of-correctness & complexity analysis