

Wersion 1.0

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1. Welcome to WinXSPort 1.0

WinXSPort lets you establish communication with an XS Board or a digital circuit through the Parallel Port of your Computer. You will be able to easily test your designs by using a Windows application.

In this manual, you will discover how to use the application WinXSPort, the different possibilities it offers and interesting comments that can help you to solve some of your problems while using it.

WinXSPort has been developed by a group of students at the College of Telecommunication Engineers (ETSIT) at the University of Valladolid (Spain). Hopefully, you will find this program useful.

1.1 Main features of WinXSPort 1.0

- It allows communication with XS Boards from XESS Corporation (http://www.xess.com/FPGA), and other external circuits.
- It has got a Graphical User Interface.
- It works on Windows'95/98/NT.
- It supports different port addresses.
- You can send signals to the board and read signals from it.
- You may select and give meaningful names to the pins used.
- Stimulus signals can be set in two ways:
 - Interactive mode: you may change the signal applied on a pin by pressing a button.
 - Defined signals: you may define a timing diagram (e.g. my signal X should be high
 5 steps, low 3 steps, and so on). Your signals will change according to that diagram.
- The signals you sent to the board, and read from it, will be displayed on the screen.
- You can store the configuration and the stimulus in a file and load it later to repeat automatically the stimulus sent to the board.

1.2 Requirements

- Windows 95/98/NT.
- DriverLINX Port I/O Driver must be installed in your computer. This driver is provided without charge by Scientific Software Tools, Inc. (http://www.sstnet.com). You can find a copy at XESS Corp. website:
 - (http://www.xess.com/FPGA/port95nt.exe)
- You should configure your parallel port in SPP mode.

2. Introduction to the Parallel Port

A very common technique to connect a PC with electronic circuits is using the Parallel Port, as it offers inputs and outputs for data which are compatible with TTL levels. Then, it is really useful to control digital circuits with a PC and be able to read data generated by the circuit.

The Parallel Port is usually placed in the back side of a computer. The Parallel Port connector is typically a 25-pin female connector, type D (DB-25).

There are several specifications for the parallel port. Some of them are:

- SPP (Standard Parallel Port): It is the original specification, being the one this document refers to. You should set your port to this mode in order to use WinXSPort.
- EPP (Enhanced Parallel Port)
- ECP (Extended Capabilities Port).

The configuration of your parallel port can be changed using BIOS. You may find more information about the different specifications at [Peacock].

2.1 Base address

You can use several registers or read/write ports to control the Parallel Port. These registers are placed in fixed memory positions. A Parallel Port is usually assigned one of these address ranges:

BASE ADDRESS	RANGE	COMMENTS
0x3BC	0x3BC - 0x3BF	It is not often used nowadays
0x378	0x378 - 0x37F	Usually used for LPT1
0x278	0x278 - 0x27F	Usually used for LPT2

Table 1: Parallel Port address and ranges

First of all, you should know the base address for the Parallel Port you are going to use.

- If you are using Windows 95, it is easy to know this address following the sequence:
 Start → Settings → Control Panel → System → Device Manager → Ports → Printer Port (LPTx) → Resources. And there you have it...
- If you are using Windows NT you can check it using BIOS.

2.2 Registers

There are three 8-bit registers (or ports) which offer interesting operations for communication with the Parallel Port:

1. **Data Register**: It is placed at the *base address* of the port and it is used to send data from the computer to an external peripheral by setting the voltage level of 8 of the pins in the DB-25 connector.

- 2. **Status Register**: It is placed at *Base address* + 1, and it is used to make the computer read data from an external peripheral. It reads the voltage level of 5 of the pins in the connector.
- 3. **Control Register**: It is placed at *Base address* + 2. Another 4 pins that can be used to send data to an external peripheral.

For example, if you want to send control signals to an external digital circuit, you can use data or control register to do it, setting bits D0 to D7 of the data register or bits C0 to C3 of the control register. If you are going to receive data from a peripheral, you can do it by reading bits S3 to S7 of the status register.

In the figure below you can see which bit in each register controls which pin in a DB-25 female connector. For instance, when you write '1' at bit 0 ot data register (D0), you will have '1' at pin 2 of the connector.

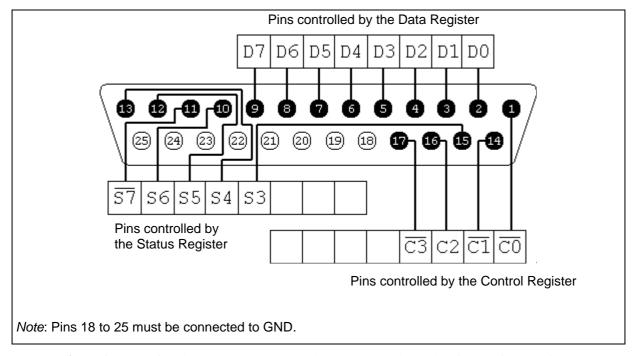


Figure 1: DB-25 female connector. Correspondence between pins and registers (after [Harries]).

In case you need further information about the parallel port and how to make applications interfacing the parallel port, you should have a look to [Peacock], [Harries] and [Anderson].

3. WinXSPort 1.0: the Application

WinXSPort lets you work with the Parallel Port of a computer, sending and receiving information from the different pins. It is especially designed so that you can send and receive data from an XS40 board¹ [Xess, VandenBout], but you can also control other devices. It is advisable to read the introduction to the Parallel Port of this manual before you use this application.

WinXSPort is very easy to use. First of all, you have to run the application. You can do it by double-clicking on the WinXSPort icon



and you will see the main window.

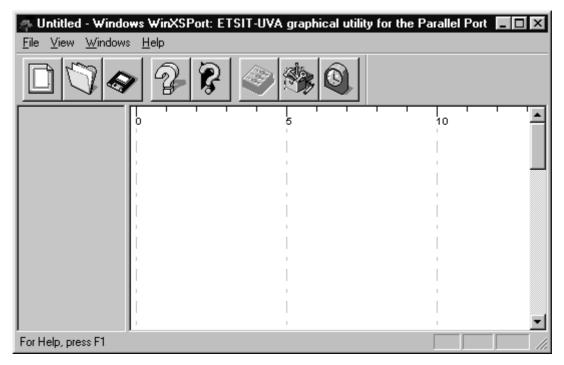


Figure 2: WinXSPort Main Window

Then, it is necessary to configure the pins, that is, to select which pins you are going to use and work with. Just press button **Configuration Window**



to make the *WinXSPort Configuration Panel* appear and set your own configuration. This process is explained with more detail in section 3.1.1.

¹ It should work with XS95 and XSP boards too.

Then, it is time for the application to be run, that is, to start sending and receiving data. Pressing button **Stimulus Control Window**



another window will appear. There, it is possible to change the values of the signals in each step and send them with button **Step**.



The application will run step by step, letting you see the state of each signal in the main window. This process will be explained in section 3.2.

3.1 Configuring WinXSPort

You should configure WinXSPort before using it: you have to indicate the Parallel Port address in your PC, select the application working mode and the pins you are going to use. You must do it in the WinXSPort Configuration Panel. You may also configure the time elapsed between sending data to the external circuit and reading the output from it. That period can be set by pressing the Timer Configuration button.

3.1.1 WinXSPort Configuration Panel

First of all, you have to indicate the Parallel Port address in your PC, select the application working mode, the pins you are going to use. You may even define the stimulus you are going to apply. All these tasks can be done in the WinXSPort Configuration Panel.

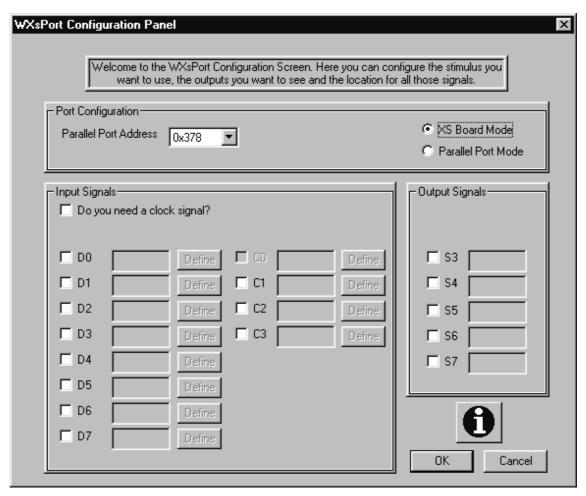


Figure 3: WinXSPort Configuration Panel

3.1.1.1 Port Address

The default port address is 0x378, but it is also possible to change it in case your application is going to be run in a machine whose Parallel Port has been assigned another address.



Figure 4: Parallel Port Address

You are given the possibility to select "Other" address, so you must be very careful with the one you write as it is going to be the base address for your next operations with Parallel Port.

3.1.1.2 Parallel Port Mode / XS Board Mode

WinXSPort allows you to choose which mode you are going to work with. It is possible to have an application running in Parallel Port Mode or in XS Board Mode. Thus, first of all, you must indicate it in the configuration window.



Figure 5: XS Board Mode / Parallel Port Mode

If you are using an XS Board, be sure this mode of operation is selected so that signals can reach the board in the correct status.

• Parallel Port Mode

This mode of operation should be used for those cases when it is necessary to connect the port with an arbitrary circuit (not an XS Board).

If you use this mode, you control and read the level of the DB-25 pins, that is, what you see on your display is what you have at the DB-25 pins. For instance, if you select the WinXSPort signals D0 and D3 to send data and S7 to read data, and you write D0 = 1 and D3 = 0, you will have 1 at pin 2 of the connector and 0 at pin 3. If the output data of the external circuit drives pin 11 of the connector to 0, the program will show 0 at signal S7.

The connection between WinXSPort signals and DB-25 pins is set as indicated in Appendix A, Table 2.

• XS Board Mode

This mode of operation should be used for those cases when you are connecting the parallel port with an XS Board.

If you use this mode, *you control and read the level of the FPGA/CPLD pins of the board*, that is, what you see on your display is what you have at the FPGA/CLPD pins. For instance, if you select the WinXSPort signals D0 and D3 to send data and S7 to read data, and you write D0 = '1' and D3 = '0', you will have '1' at pin 44 of the PLD and '0' at pin 45. If your design drives pin 75 of the PLD to '0', the program will show '0' at signal S7.

The connection between WinXSPort signals and XS Board pins is set as indicated in Appendix A, Table 3. Keep in mind that you will not be able to choose signal C0 as it is connected to the /PROGRAM pin of the FPGAs.

IMPORTANT: Remember that if you are using an XS Board in your application you must use XS Board Mode since if you use Parallel Port Mode instead, the FPGA will clear its configuration memory.

If you press button **Information**,



a window will be displayed showing the connection between WinXSPort signals and DB-25 or XS Board pins.

3.1.1.3 Clock Signal



Figure 6: Clock Signal

WinXSPort defines a default clock in case you need a clock signal for your application. Then, clock is always assigned to pin D0, so you will not be able to use this pin for anything else. The clock changes its state (1 - 0) in each step, that is, when pressing button **Step** at the Stimulus Control. Therefore: 1 step = 1 half-cycle. You can choose if you want the clock to start at level 0 or 1.

3.1.1.4 Signal Choice and Signal Definition

Now, you have to indicate which signals, and therefore which pins, you are going to work with. Thus, you must select those checkboxes you are interested in. You may give a meaningful name to the signal.



Figure 7: Signal choice

Once the signals have been chosen, it is possible to define them so as to have the necessary state for the signal. You can define periodic or non-periodic signals as it is possible to choose the number of half-cycles or steps in high/low status.

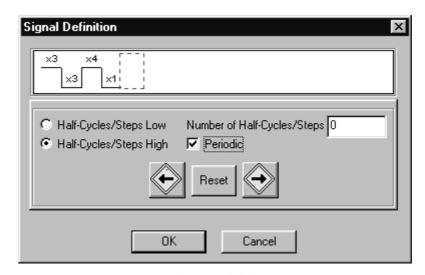


Figure 8: Signal Definition

In the figure, a signal has been defined: it is 3 cycles high, 3 cycles low, 4 cycles high and 1 cycle high, and it has been made periodic by marking the checkbox. You must write the number of cycles in the edit box, indicate if it is low/high and then press right arrow to continue. It is important to know that you must press "right" arrow to really introduce the signal. It is also possible to go back by pressing left arrow and redefine the sequence by changing the value in the edit box. You will see, at the same time, how your signal is being defined in the graph above. When you have finished, you must press button OK.

It is not mandatory to define the signals you are going to use, you may change its status interactively later.

3.1.2 Timer Configuration

You can set the minimum allowable time between write/read operations: default is 100 msecs. If you are controlling the generation of signals in a digital circuit and you know that the time spent by your circuit to generate outputs from input is 150 msecs, you may be interested in reading the outputs of your circuit at least 150 msecs after the inputs are given, so you must click button



and set your timer.

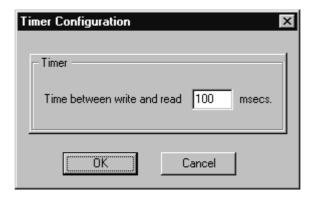


Figure 9: Timer Configuration Window

Then, this timer is used to set the minimum time between writing signals Dx/Cx and reading signals Sx. The minimum time is 1 ms., but since Windows is not a real-time operating system, if you specify a timer of less that 100 ms. it will not be accurate.

3.2 Running the Application: Sending and Receiving Data

Once the configuration is set, you are ready to run the application and establish communication with the Parallel Port, sending and receiving data to/from it. You only have to press button **Stimulus Control Window**:



Then, a new window will appear where you can interactively change signals status.

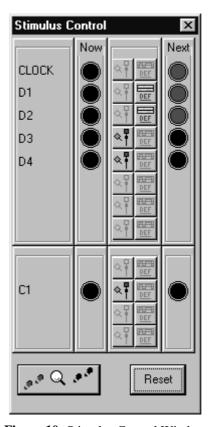


Figure 10: Stimulus Control Window

In the stimulus control dialog, you can see the signals you are working with (only those associated with Dx and Cx but not the ones associated with Sx) and their current and next status (on/off).

- Pressing the **Switch** button you may change the signal status interactively, if it has not been defined. If you have defined a non-periodic signal that lasts N cycles, this switch button will not be enabled until cycle N+1. This button is not enabled for periodic signals.
- Pressing the **Repeat Sequence** button, the signal will follow the sequence previously defined. For example, you may have defined a signal to as: 1 1 0 1 0, and every time you press this button it will follow that sequence. This button is not enabled for periodic signals.

3.2.1 Step and Reset

In order to continue, step by step, you must press button **Step**



and the main window will be updated with the status of all the selected signals. It will send the input to the external circuit or board and, afterwards, it will read the output provided.

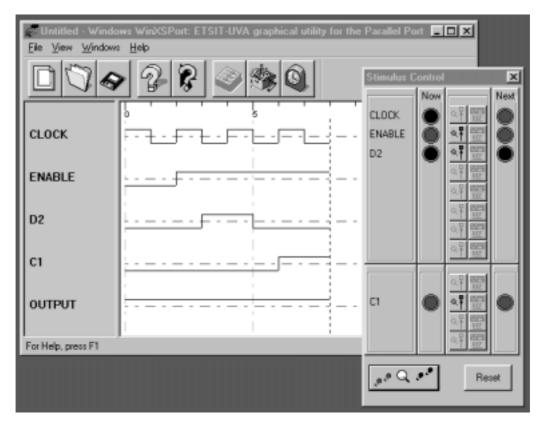


Figure 11: Different signals during the execution

In the figure above you can see the signals the application is using: names in the left frame and their corresponding status.

When pressing the **Reset** button the signals waveforms displayed on the right frame of the window will be cleared, but signals will not change to their initial state (reset doesn't mean to make a "Power-on" but just clear the window).

3.2.2 Reconfiguration of signals

It is also possible to reconfigure the state of the signals, select new signals, remove others, etc. whenever necessary, opening WinXSPort Configuration Panel with button Configuration Window



and if you also want to define new signals, you must press button **Define**

Define

and follow indications in 3.1.1.4.

3.3 Save and Load

Now, if you want to save your current workspace (your configuration and stimulus history), you can do it by pressing button **Save**



or selecting option Save in the File Menu.

And if you want to load a previous workspace you only have to press button **Open**



or select option *Open* in the *File Menu*. Thus, the new configuration will be set and the stimulus will be applied. Loading of a file is slow since it repeats all the process, that is, it repeats the stimulus applied to the board/circuit.

Imagine that you are testing the design of a filter in an XS Board, and when applying some stimulus (maybe 60 or 70 steps long) it fails. You may save the configuration and stimulus in a file (e.g. *filter.sti*), then you could redesign your filter, download it to the board, and once it is downloaded you could open the file *filter.sti*. Thus, the stimulus will be automatically applied to the board so you just have to check whether the results are OK now or not.

4. Example: Control of a counter

We want to implement a counter in an FPGA placed in an XS40 Board. Using Xilinx Foundation Series, our design is:

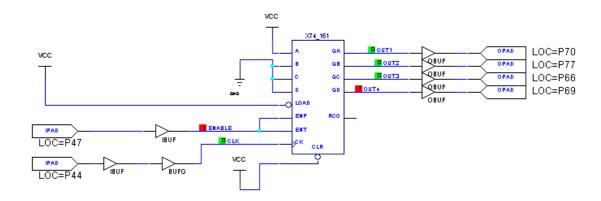


Figure 12: Counter design

As said before, this design is going to be implemented in an XS40 Board, thus, we must work in XS Board Mode, and it will be necessary to know which are the connections between the FPGA, the Parallel Port and the DB-25 Connector (Appendix A, table A.2).

- \Rightarrow In this design, inputs are:
- **Clock Signal**: Pin 44 of the FPGA is used, which corresponds to input signal D0 of WinXSPort. As we are using Board Mode, when we write '1' in the program, there will also be '1' in pin 44 of the FPGA (*idem* with 0).
- **Enable**: Pin 47 of the FPGA is used, which corresponds to input signal D3.
- ⇒ Counter outputs are placed in pins 70, 77, 66 and 69 of the FPGA, which correspond to WinXSPort signals S3, S4, S5 and S6, respectively.

So, the configuration we are going to use in WinXSPort is shown in the figure below:

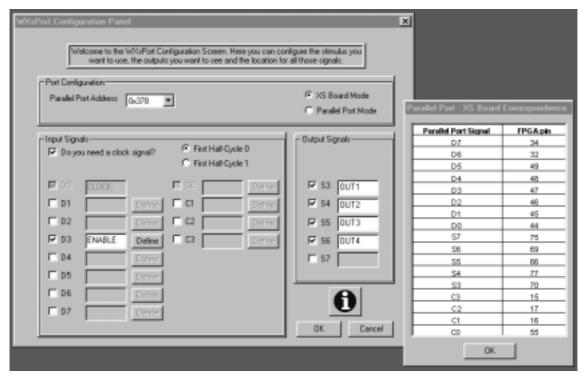


Figure 13: Configuration Panel

As said before, we must use both a clock signal (D0) and an enable signal (D3). This one can be defined in this dialog box, pressing **Define** or change its status interactively later.

In the figure below, you can see the different signals. In the outputs, OUT1 is the LSB and OUT4 is the MSB. The counter has performed 0, 1, 2 ... 9, ... and it began when the enable signal was set to '1'.

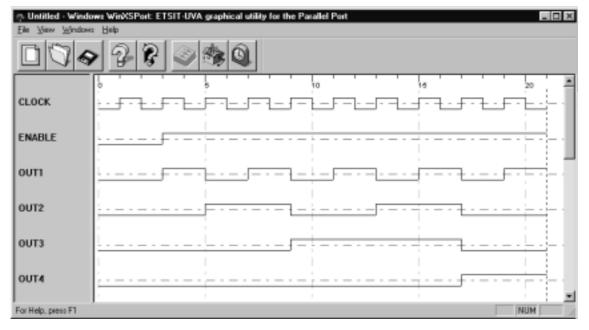


Figure 14: Main window with the outputs given by WinXSPort

5. Help

Apart from this manual, you can also get on-line help for the application. You can access this help by two different means: using the help file provided with WinXSPort or directly from the application.

5.1 Help file

You can access help by double clicking on icon "WinXSPort Help". A window dialog with three tabs (contents, index and search) will appear.

• Contents

Clicking on the books you will find complete information about the possibilities of WinXSPort, a guide to get used to working with it, know the different options, steps, buttons. Graphs and icons are provided in order to help using it.

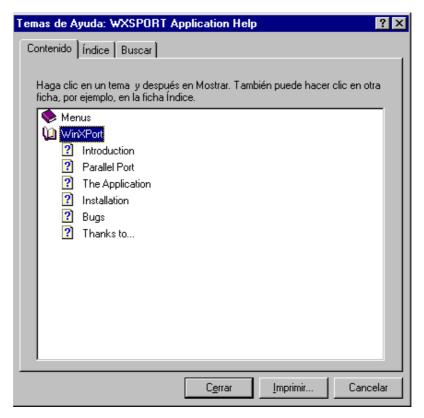


Figure 15: Application help: contents

• Index

A list of topics is provided, so you can choose one of them directly. But you can also write the first letters of the topic you are interested in.

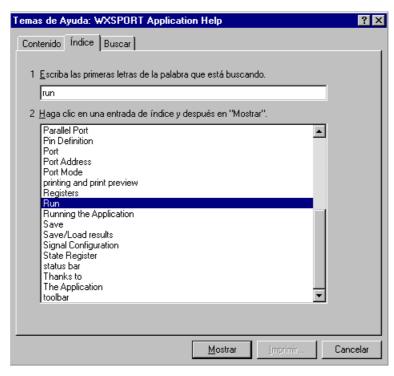


Figure 16: Application help: index

• Search

Here, you can search words, expressions related to topics, etc. You must write the word you are interested in and you will obtain a list of topics which contain this word or pages on which this word is present.

The first time you use this operation, the list of words and database for the help will be created.

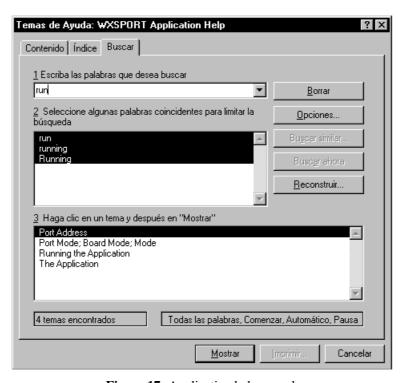


Figure 17: Application help: search

5.2 Help in the Application

Help for the application is accessed when clicking *Help* in main menu. You will obtain the same dialog window as before. In addition, it is also possible to obtain help for some topics by clicking button **Help** directly from the application



and then clicking the object. For example, if you want to know what the button



is used for, you must click **Help** button first and then, when the mouse has changed into an arrow and a '?', you must press button **Configuration Window** and you will obtain help for it.

6. Install / Uninstall

To install the program or new options execute wxsetup.exe, and follow the instructions.

To unistall execute the Uninstall program and click **Start**. Press **Quit** when the process has finished.

7. FAQs

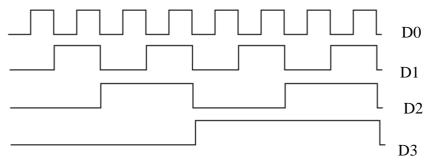
• The application doesn't take the last value of the signal when I try to define it. It is important to know that you must press the "right" arrow to really introduce the signal, that is, after indicating the number of high/low level cycles, press button



to make the software know the new value.

• How can I define a counter from 0 to 15?

First of all you have to select signals D0, D1, D2 and D3 (data register) in the configuration panel (Figure 3). Then in signal definition dialog (Figure 8), you must define signals as follows:



In order to get help about how to choose and define signals, you can go to section 3.1.1.4. Then, in each step of the execution of the application, you will obtain values in pins D0 ... D3 corresponding to $0, 1, 2 \dots 15$.

• Part of my left frame has disappeared, what should I do?

Just click in the vertical scroll bar. It will synchronize then with the right frame of the window.

• A message box has appeared indicating that the application has come to an end, what can I do to continue the execution?

The length of the execution of the application is finite: 999 steps and then a message box will notify it. If you want to continue the execution, you must press **Reset** button to clear the window, and then you can go on by pressing button **Step**.

• I have opened a file and have modified it but now I would like to open the saved version: I can't do it, as the software ignores me. What can I do?

Press *New* in the toolbar menu, and don't save the changes when you are asked to, and then open the file.

• I'm using Xilinx Foundation Series and an XS40 board, and would like to use pins 32, 34, 75, 15, 17 and 16 of the FPGA, but I'm getting errors like "Bad format for LOC constraint P32 on IPAD symbol..." when implementing my design. Why?

All those pins are special pins of the FPGA. Instead using an IPAD or an OPAD you should use a special library component. Take a look at Table 3 at Appendix A, where you will find the component you should use in each case.

• Why are there two different configuration modes?

In XS Board Mode, the application is in charge of some of the signals (e.g. D0, D1) which are connected to NOT gates in the board, and it assures that the values the user introduces are going to be those which appear in the correspondent pin of the FPGA. For example, let's use signal D0. This signal is related to pin 2 of the DB-25 connector, and it is also connected, going through a NOT gate, to pin 44 of the FPGA. Thus, when working in Parallel Port Mode and D0 = 1, the application assures that pin 2 of the DB-25 connector, that is, the correspondent pin connected to D0, is also set to this value. But if you are

working in XS Board Mode and set D0 to '1', this is also going to be the value that you will get in pin 44 of the FPGA.

		Pin 2 DB 25 Connector	Pin 44 FPGA
Parallel Port Mode	D0 = 1	1	0
XS Board Mode	D0 = 1	0	1

TABLE 2.1 Port Mode / Board Mode

Then, as indicated above, WinXSPort takes care of all these problems so the user only has to know in which mode he/she wants to work and make sure the introduced values are those needed for the application. Remember that if you are using the XSBoard in your application you must use XS Board Mode since if you use Parallel Port Mode instead, the FPGA will clear its configuration memory.

• When using the clock (D0), how do you write and read signals? Do you take into account set-up time?

We write the data register and control register. Afterwards, we write the data register again but with the clock signal changed. Then, after holding on some time (as set in the Timer Configuration window) we read the status register, that is, the data sent from the external circuit to the PC. Since all the data (D1-D7, C0-C3) are written before the clock change (about 1 μ s. before, although it depends on the computer) there should be no problems with set-up time (some ns. [Xilinx]). When testing your design with WinXSPort, bear in mind that data D0-D7 is sent before data C0-C3 to the board.

8. Known Problems

- The length of the execution of the application is finite: 999 steps and then a message box will notify it. To see how to solve this problem see the section 7 (FAQs).
- The length of the definition of signals is also finite and a message box will notify it.
- Sometimes, part of the frame with the names of the signals disappears. You will solve it clicking on the vertical scroll bar.
- Clicking in the left frame makes the configuration and stimulus buttons to deactivate. Click in the right frame and they will be active again.
- If you have defined some signals for your application and, some time later, you define some more, the "history" of the new signals will be set to zero as can be seen in the figure below. In general, you should add all the signals used before starting sending data to the external circuit.

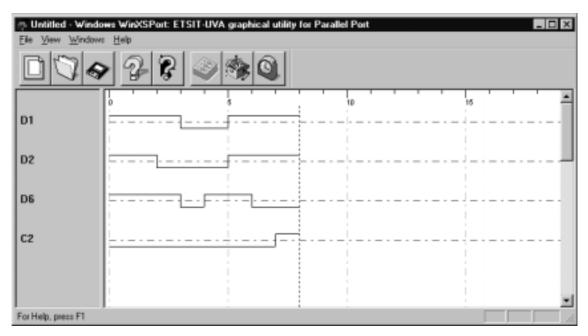


Figure 18: Signal C2 was defined after 7 steps

9. Thanks to...

Thanks to Prof. Ma Eugenia Llamas for reviewing the English version of this manual. Thanks to Xess Corporation, specially to Dr. Dave Van den Bout, for donating an XS40 board for the project.

10. About us ...

WinXSPort has been developed by Gonzalo Martín de Mercado Pérez, Francisco A. Lago García, and T. Paloma Ortega Camarero under the direction of Prof. Ignacio de Miguel Jiménez.

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This software can also be downloaded from XESS Corp. Website (http://www.xess.com/FPGA).

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12. APPENDIX A: Connection schemes

If you are going to work in Parallel Port Mode, that is, you are working with an external circuit or you simply need the signals sent to the Parallel Port, you must know that the connections between the registers which control de Parallel Port and the pins in the DB-25 connector are as indicated below:

WinXSPort Signal	DB-25 Connector pin
D7	9
D6	8
D5	7
D4	6
D3	5
D2	4
D1	3
D0	2
S7	11
S6	10
S5	12
S4	13
S3	15
C3	17
C2	16
C1	14
C0	1

Table 2: Connections between the registers and the DB-25 Connector

But this application has been primarily intended to establish communication between the Parallel Port of the computer and XS40 Boards. In this case, the connections made are as indicated below. We have also written the library component you should place in your schematic in order to use each pin. In general, you just need an IPAD or an OPAD (and an IBUF/OBUF), but sometimes you need other components (in this special cases, just place the component and the IBUF/OBUF but do not set the parameter LOC=Pxx).

WinXSPort Signal	XS40/FPGA pin	Symbol
D7	34	MD2
D6	32	MD0
D5	49	IPAD
D4	48	IPAD
D3	47	IPAD
D2	46	IPAD
D1	45	IPAD
D0	44	IPAD
S7	75	TDO
S6	69	OPAD
S5	66	OPAD
S4	77	OPAD
S3	70	OPAD
C3	15	TDI
C2	17	TMS
C1	16	TCK
	55	
C0	(Not used by WinXSPort)	_

Table 3: Connections with an XS40 Board

If you are using an XS95 board you should take into account the following table

WinXSPort Signal	XS95/CPLD pin
D7	80
D6	81
D5	52
D4	51
D3	50
D2	48
D1	47
D0	46
S7	59 (TDO)
S6	70
S5	66
S4	72
S3	71
C3	28 (TDI)
C2	29 (TMS)
C1	30 (TCK)
C0	6 (Not used by WinXSPort)

Table 4: Connections with an XS95 Board