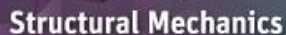


Appendix A

Eigenvalue Buckling Analysis

16.0 Release

A visualization of fluid flow, showing blue, wavy, translucent streamlines that represent the movement of a fluid around an object, though the object itself is not clearly defined.A 3D model of a purple gear with a glowing white and purple center, set against a background of other, fainter gears, representing structural analysis.A series of concentric green and white circles, resembling a target or a cross-section of a magnetic field, representing electromagnetic analysis.A 3D arrangement of blue and black cubes, some of which are stacked or connected, representing a complex system or multiphysics simulation.

Introduction to ANSYS Mechanical

In this Appendix, performing an eigenvalue buckling analysis in Mechanical will be covered.

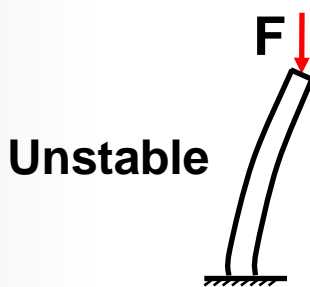
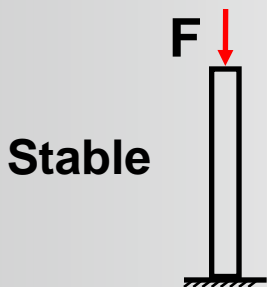
Mechanical enables you to link the Eigenvalue Buckling analysis to a *nonlinear* Static Structural analysis that can include all types of nonlinearities. This will not be covered in this section. We will focused on Linear buckling.

Contents:

- A. Background On Buckling
- B. Buckling Analysis Procedure
- C. Workshop AppA-1

Many structures require an evaluation of their structural stability. Thin columns, compression members, and vacuum tanks are all examples of structures where stability considerations are important.

At the onset of instability (buckling) a structure will have a very large change in displacement $\{\Delta x\}$ under essentially no change in the load (beyond a small load perturbation).



Eigenvalue or linear buckling analysis predicts the theoretical buckling strength of an *ideal linear elastic* structure.

This method corresponds to the textbook approach of linear elastic buckling analysis.

- The eigenvalue buckling solution of a Euler column will match the classical Euler solution.

Imperfections and nonlinear behaviors prevent most real world structures from achieving their theoretical elastic buckling strength.

Linear buckling generally yields *unconservative* results by not accounting for these effects.

Although *unconservative*, linear buckling has the advantage of being computationally cheap compared to nonlinear buckling solutions.

For a *linear buckling analysis*, the eigenvalue problem below is solved to get the buckling load multiplier λ_i and buckling modes ψ_i :

$$([K] + \lambda_i [S])\{\psi_i\} = 0$$

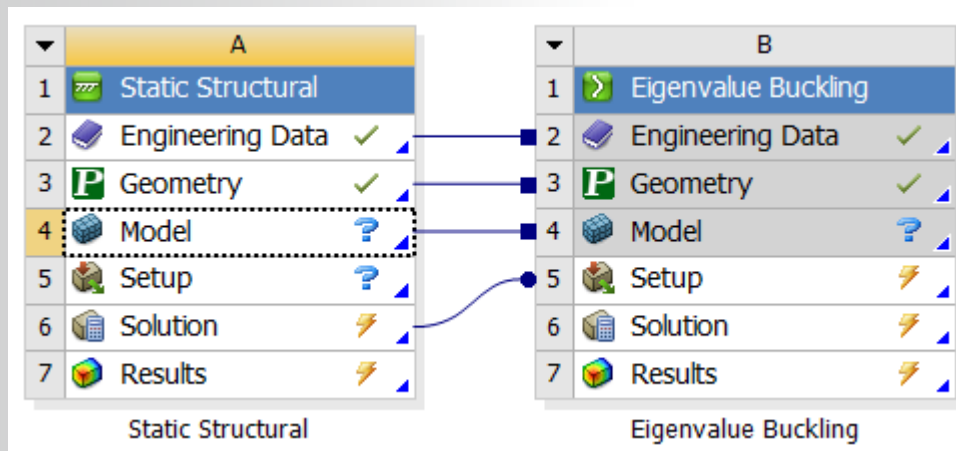
Assumptions:

- [K] and [S] are constant:
 - Linear elastic material behavior is assumed
 - Small deflection theory is used, and *no* nonlinearities included

It is important to remember these assumptions related to performing *linear buckling analyses* in Mechanical.

B. Buckling Analysis Procedure

A Static Structural analysis will need to be performed prior to (or in conjunction with) a buckling analysis.



Any type of geometry supported by Mechanical may be used in buckling analyses:

- Solid bodies
- Surface bodies (with appropriate thickness defined)
- Line bodies (with appropriate cross-sections defined)
 - Only buckling modes and displacement results are available for line bodies.
- Although Point Masses may be included in the model, only inertial loads affect point masses, so the applicability of this feature may be limited in buckling analyses

For material properties, *Young's Modulus* and *Poisson's Ratio* are required as a minimum

Contact regions are available in free vibration analyses, however, contact behavior will differ for the *nonlinear* contact types exactly as with modal analyses.

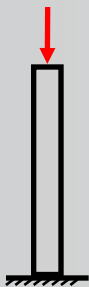
(see chapter 8 of the Mechanical Introduction course for further details).

Contact Type	Linear Buckling Analysis		
	Initially Touching	Inside Pinball Region	Outside Pinball Region
Bonded	Bonded	Bonded	Free
No Separation	No Separation	No Separation	Free
Rough	Bonded	Free	Free
Frictionless	No Separation	Free	Free

At least one structural load, which causes buckling, should be applied to the model:

- All structural loads will be multiplied by the load multiplier (λ) to determine the buckling load (see below).
- Compression-only supports are not recommended.
- The structure should be fully constrained to prevent rigid-body motion.

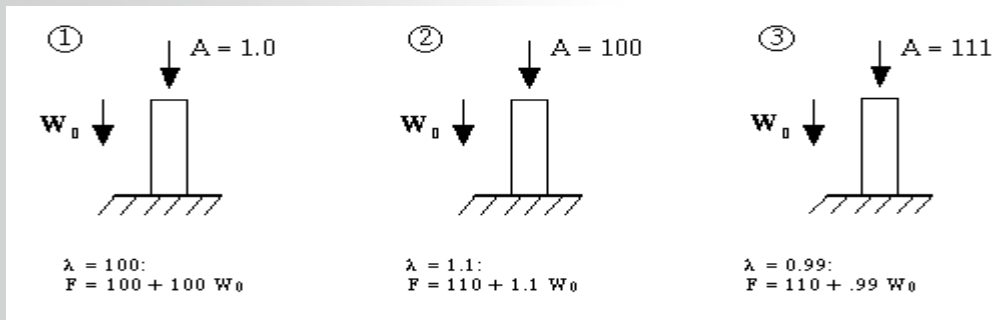
$$F \times \lambda = \text{Buckling Load}$$



In a buckling analysis all applied loads (F) are scaled by a multiplication factor (λ) until the critical (buckling) load is reached

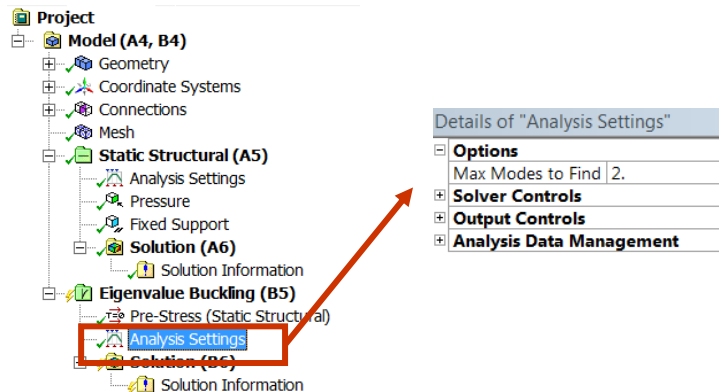
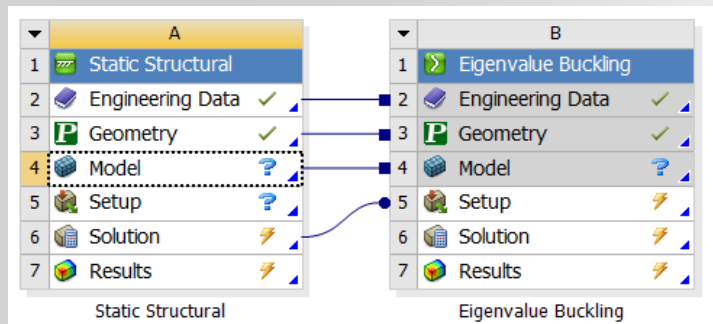
Special considerations must be given if constant *and* proportional loads are present.

- The user may iterate on the buckling solution, adjusting the variable loads until the load multiplier becomes 1.0 or nearly 1.0.
- Consider the example of a column with self weight W_0 and an externally applied force A .
- A solution can be reached by iterating while adjusting the value of A until $\lambda = 1.0$. This insures the self weight = actual weight or $W_0 * \lambda = W_0$.



Buckling analyses are always coupled to a structural analysis within the project schematic.

- The “Pre-Stress” object in the tree contains the results from a structural analysis.
- The Details view of the “Analysis Settings” under the Linear Buckling branch allows the user to specify the number of buckling modes to find.



Details of "Analysis Settings"

Options	Max Modes to Find 2.
Solver Controls	
Output Controls	
Analysis Data Management	

In the details view, under solver controls, user can include negative load multiplier.

Details of "Analysis Settings"	
Options	
Solver Controls	
Solver Type	Program Controlled
Include Negative Load Multiplier	Program Controlled
Output Controls	
Analysis Data Management	

After setting up the model the buckling analysis can be solved along with the static structural analysis.

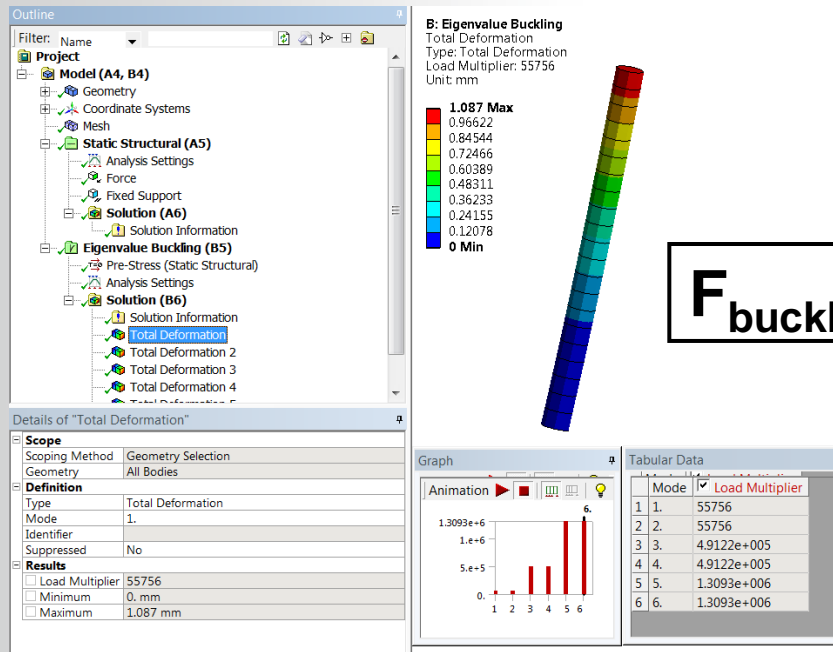
- A linear buckling analysis is *more computationally expensive* than a static analysis on the same model.
- The “Solution Information” branch provides detailed solution output.

The screenshot displays the ANSYS Workbench interface. On the left, the Project Schematic shows a hierarchy: Model (A4, B4) containing Geometry, Coordinate Systems, Mesh, Static Structural (A5), and Solution (A6). Under Solution (A6), the 'Solution Information' branch is highlighted with a red box. Below the schematic, the 'Details of "Solution Information"' panel shows fields for Solution Output, Newton-Raphson Residuals, Update Interval, and Display Points. On the right, the Solution Output window displays the results of the buckling analysis, including Eigenvalues, Element Result Calculation Times, Nodal Load Calculation Times, and ANSYS Binary File Statistics.

```
***** EIGENVALUES (LOAD MULTIPLIERS FOR BUCKLING) *****  
*** FROM BLOCK LANCZOS ITERATION ***  
  
SHAPE NUMBER    LOAD MULTIPLIER  
  
1                55755.631  
2                55755.631  
3                491215.29  
4                491215.29  
5                1309290.6  
6                1309290.6  
  
*** ELEMENT RESULT CALCULATION TIMES  
TYPE  NUMBER  ENAME      TOTAL CP  AVE CP  
1      21     BEAM188    0.187    0.008914  
2      3      CLOAD201    0.000    0.000000  
  
*** NODAL LOAD CALCULATION TIMES  
TYPE  NUMBER  ENAME      TOTAL CP  AVE CP  
1      21     BEAM188    0.000    0.000000  
2      3      CLOAD201    0.000    0.000000  
  
*** ANSYS BINARY FILE STATISTICS  
BUFFER SIZE USED= 16384  
0.125 MB WRITTEN ON ELEMENT MATRIX FILE: file.emat  
0.750 MB WRITTEN ON ELEMENT SAVED DATA FILE: file.esav  
0.062 MB WRITTEN ON ASSEMBLED MATRIX FILE: file.full  
0.062 MB WRITTEN ON MODAL MATRIX FILE: file.mode  
0.562 MB WRITTEN ON RESULTS FILE: file.rst  
***** Write FE CONNECTORS *****
```

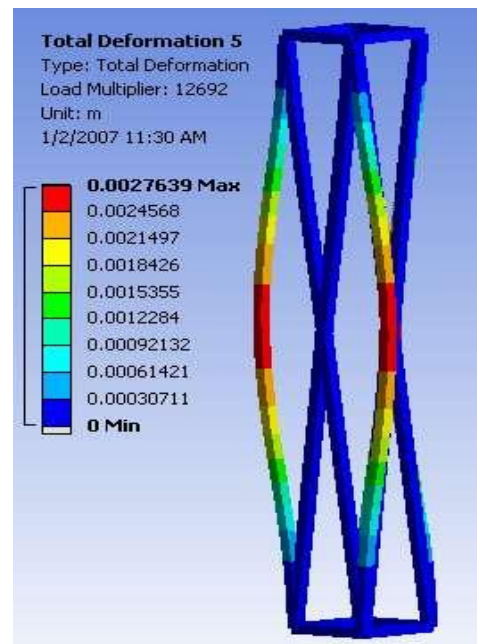
After the solution is complete, the buckling modes can be reviewed:

- The Load Multiplier for each buckling mode is shown in the Details view as well as the graph and chart areas. The load multiplier times the applied loads represent the predicted *buckling load*.



Interpreting the Load Multiplier (λ):

- The tower model below has been solved twice. In the first case a unit load is applied. In the second an expected load applied (see next page)



Interpreting the Load Multiplier (λ):

Details of "1st Buckling Mode"	
[-] Scope	
Geometry	All Bodies
[-] Results	
<input type="checkbox"/> Load Multiplier	29008

$$\text{BucklingLoad} = \lambda * \text{Unit_Load}$$

$$\Rightarrow \text{BucklingLoad} = \lambda$$

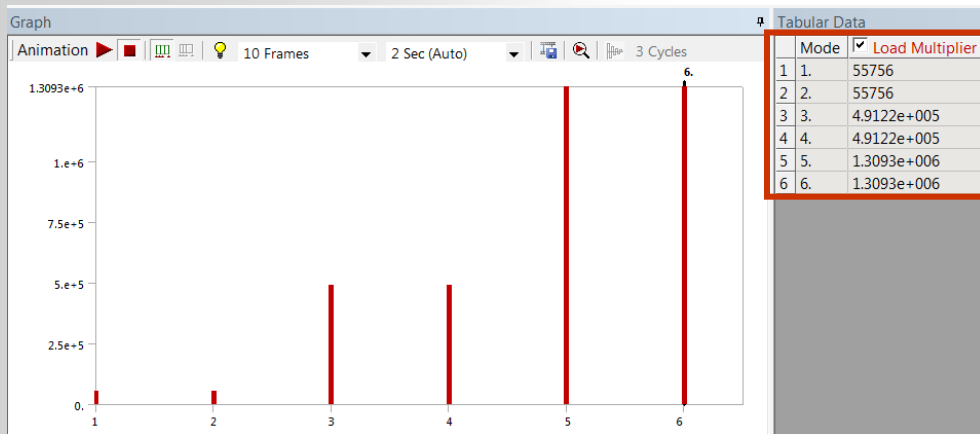
Details of "1st Buckling Mode"	
[-] Scope	
Geometry	All Bodies
[-] Results	
<input type="checkbox"/> Load Multiplier	1.0003

$$\text{BucklingLoad} = \lambda * \text{Actual_Load}$$

$$\Rightarrow \frac{\text{BucklingLoad}}{\text{Actual_Load}} = \lambda = \text{Safety_Factor}$$

The buckling load multipliers can be reviewed in the “Timeline” section of the results under the “Linear Buckling” analysis branch

- It is good practice to request more than one buckling mode to see if the structure may be able to buckle in more than one way under a given applied load.



- Workshop Appendix A - Buckling

